

THERMOACTUATOR									
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	cod. 10.0331.00								
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Descrizione delle modifi	che/ Description of the chang	66.							
14 06/07/18	Replaced the definition of lo inserted tab terminals resist	w energy" with "lo							
13 23/06/17	Update paragraph 5.2		ion, apacito or graphico.						
12 01/07/13	Revision of temperature dat	a, consumption, r	emoval of marking table						
11 21/01/10	Added UL-CSA mark on ver	sion at 12-24 Vol	t.						
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GENERAL 1

1.1 Purpose of the specification

To define the characteristics and performance of the product subject of this specification. In case of contrast between the technical data reported in this specification and that which is indicated in ELTEK drawings, the latter will prevail.

1.2 Subject

Thermoelectric device called thermoactuator code 100331.xx.

The thermoactuator is a small device which, through a mobile plunger, performs a gradual stroke overcoming a determined reaction force. This operation is absolutely silent and practically with no electromagnetic emissions.

The thermoactuators available perform 6 or 8 mm strokes.

Among the different types it is possible to have:

- thermoactuators "long time ON", when energized for more than 2 minutes; thermoactuators "short time ON", when energized for max. 2 minutes;
- _

silicone injected thermoactuators, suitable for applications in high humidity ambients and/or in the presence of dust and pollution in the air.

Characteristics common to all versions:

- reaction force up to 100 N;
- _ voltage feed 12/24 V or 110/240 V.

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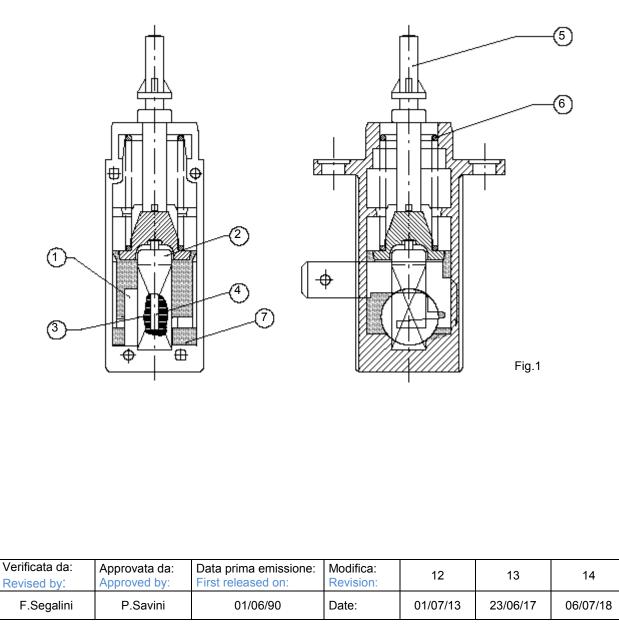
1.3 Description

The thermoactuator consists of a thermoplastic housing encorporating mounting details, two terminals for electrical connection. The housing also encloses the following elements:

A PTC (Positive Temperature Coefficient) thermistore ①, attached to one side of the wax motor. A square section metal body ②, called "wax motor" which contains a substance sensitive to heat ③ which, as it expands at a defined temperature, causes a pin ④ to move outwards and consequently originate a stroke.

A plunger in thermoplastic material (5) transfers the movement outwards; a helical spring (6) guarantees its retraction.

The version silicon injected is with extra protection from dust and moisture, an insulating substance \bigcirc is injected inside the housing itself so as to increase insulation from the exterior





1.4 Principle of operation

There is a temperature rise of the PTC when it is energized electrically; the heat produced is transferred to the wax motor.

The substance, sensible to heat, expands and gradually pushes the plunger out of the housing.

When the PTC is de-energized the wax motor cools down and the plunger, assisted by a spring, retracts to the initial position.

1.5 General characteristics

- capable of developing a considerable force in respect to its small size; particularly if compared with the size of an electromagnet of equal performance;
- operates safely even if energized continuously;
- operates at different voltages;
- absolute silent when operating;
- no E.M.I. (Electromagnetic Interference);
- gradual movement;
- easy to mount/adaptability;
- operates in critical ambient conditions:

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2 CONSTRUCTION FEATURES

2.1 Reference standards

EN 60730-1 ; EN 60730-2-14 ; EN 60335-1 ; EN 61210

2.2 Marks

The thermoactuator is certified by IMQ, European Institute of the Mark of Quality, (ENEC 03), in conformity with standards EN 60730-1 and EN 60730-2-14. Some versions of thermoactuators (indicated in the referred drawing) are certified by UL (USA) and CSA (Canada) Institutes.

2.3 Limit operating conditions of the thermoactuator

 relative humidity 	: 30% ÷ 95% for standard versions
-	: 30% ÷ 98% for silicone injected version
 ambient temperature 	: -10°C ÷ 90°C

Methods of testing for verifying limit operating conditions: Test in climatic room - 21 cycles (16h @ 40°C e 95%H.R. / 8h @ 13°C e 95%H.R. /16h @ 60°C <9% H.R.). During the climatic test, the thermoactuator is energized with 3 cycle ON / 12' OFF at 220Vac.

Test in oven with power supply 2h ON/30 min OFF at 70°C and 70% H.R. steadily for 350 cycles (700 hours in phase ON)

The thermoactuator is also certified, according to EN 60730-1 & EN 60730-2-14, for a safe limit operating temperature of 105°C.

At the temperature > 95°C the termoactuator will start to push the plunger even without electrical supply and is not guaranteed to return to its original position.

The running time performance is shown in the diagram running time cod. 12.0096.XX

2.4 Connection characteristics

There are available versions with Rast 2.5 connection and versions with connection through faston 6.3x0.8 mm: the last ones are in accordance with EN 61210.

2.5 Warehousing limit conditions/ not in operation

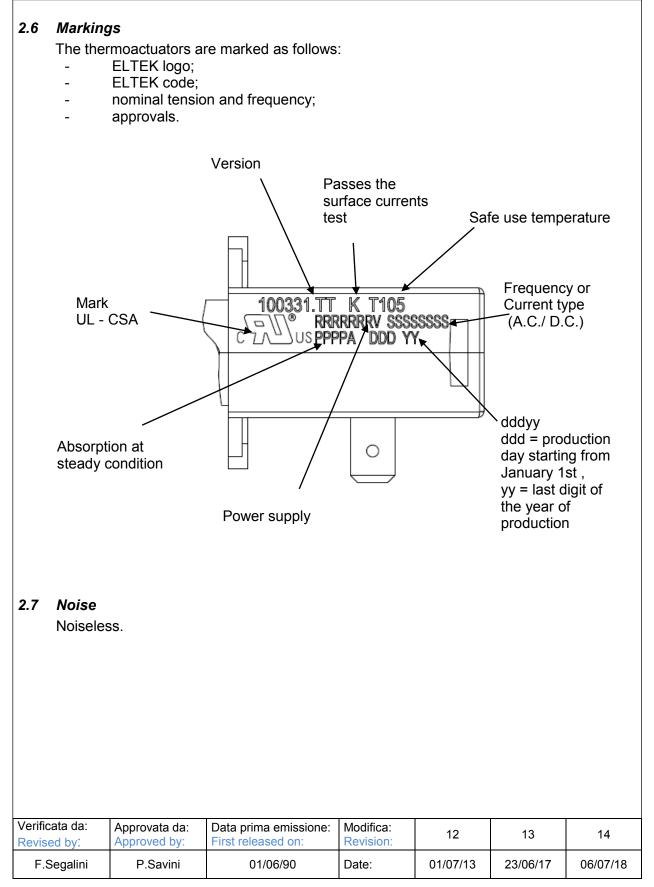
- ambient temperature : -30°C ÷ 80°C
- relative humidity : 30% ÷ 98%

NOTE: before using the component, the stabilization of the piece at temperatures higher than -10°C is requested.

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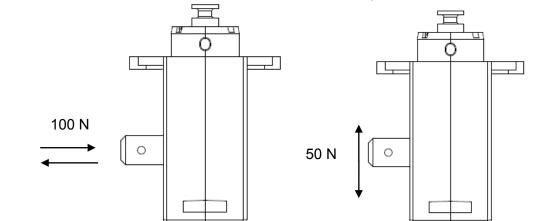
3 MECHANICAL FEATURES

Unless otherwise specified, the following characteristics are verified under the following conditions:

- Ambient temperature = $25 \pm 5^{\circ}C$
- Relative humidity = 45 ÷ 75%

3.1 Tab terminals resistance to traction / compression

Resistance of the tab terminals to a force of 100 N along their axis, both in traction and in compression; resistance to stress equal to 50 N in all other directions, without deformations such as to impair its operation or safety.

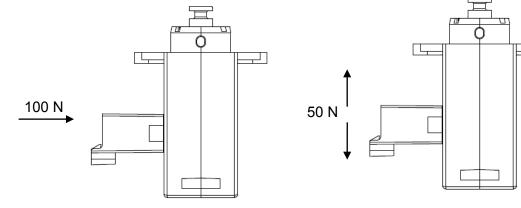


3.2 Tab terminals resistance for rast version

Resistance of the rast version to a force of 100 N along their axis, both in traction and in compression; resistance to stress equal to 50 N in all other directions, without compromising its operation or safety

Plug in force in rast connector <30N

Plug off force of the connector >=35,6N (applied at the harness)



3.3 Resistance to fall

No damage will occur to the actuator such as to impair its operation or safety if dropped on a cement surface from a height of 100 cm.

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4 PHYSICAL-CHEMICAL CHARACTERISTICS

Unless otherwise specified, the following characteristics must be verified at ambient temperature = $25 \pm 5^{\circ}$ C and relative humidity = $45 \div 75\%$

4.1 Resistance to corrosion of the metal parts

According to EN 60335-1 par. 31.

4.2 Resistance to humidity

Grade of protection against ingress of water: IP 00 (not protected, ref. IEC 60529). Resistance to humidity conditions: according to EN 60730–2–14 par. 12.2. Even if the "silicone injected" actuator doesn't obtain a higher degree of IP protection, it can work under severe environmental and relative humidity conditions (see 2.2 operating conditions).

4.3 Resistance to heat and fire

According to EN 60730–2–14 par. 21.

The thermoactuator plastic materials in contact with the live parts are classified as selfextinguishing V0 (0.8 mm) according to UL94.

The thermoactuator also successfully passes the sphere test at 140°C ref. EN 60335-1 par. 30.1

4.4 Resistance to surface currents

According to EN 60730–2–14 par. 21.

A resistance to the PTI 250 surface currents of is guaranteed for the plastic materials of the thermoactuator in contact with the live parts, according to IEC 60112.

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5 ELECTRICAL CHARACTERISTICS

5.1 Voltage feed

Voltage feed range available:

- 110 $\div 240~V_{AC}$ at 50 \div 60 Hz.
- 12 \div 24 V_{AC} at 50 \div 60 Hz
- 12 \div 24 V_{DC}

5.2 Power absorbed steady state

Power absorbed steady state after ON time (in the chart) The power is less or equal to the under-mentioned values:

	110V [W]	220V [W]	Testing time [s]
Long ON time	6,5	7,6	300
Short ON time	6,6	7,6	120

	12V [W]	24V [W]	Testing time [s]
Long ON time	3,2	3,8	300
Long ON time "Low absorption peak"	4,4	4,4	300

*Values detected at room temperature of 25°C

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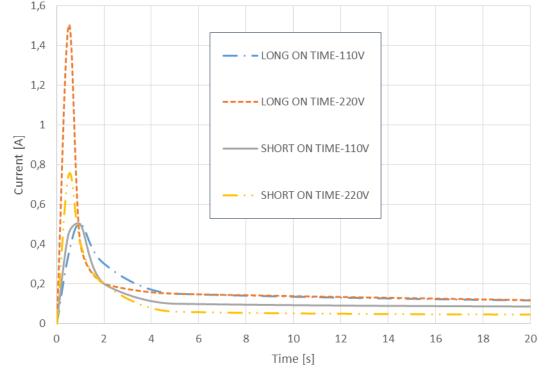


5.3

SPECIFICA TECNICA **TECHNICAL SPECIFICATION**

A representative diagram variation of current absorption vs time. The curves are diversified by the type of thermoactuator and voltage. The diagram has been obtained with: thermoactuators with a 6 mm nominal stroke; thermoactuators energized for more than 5 minutes; without counteracting load; ambient temperature 25°C. 1,6 1,4 - LONG ON TIME-110V 1,2 ---- LONG ON TIME-220V

Characteristic curve Power/time

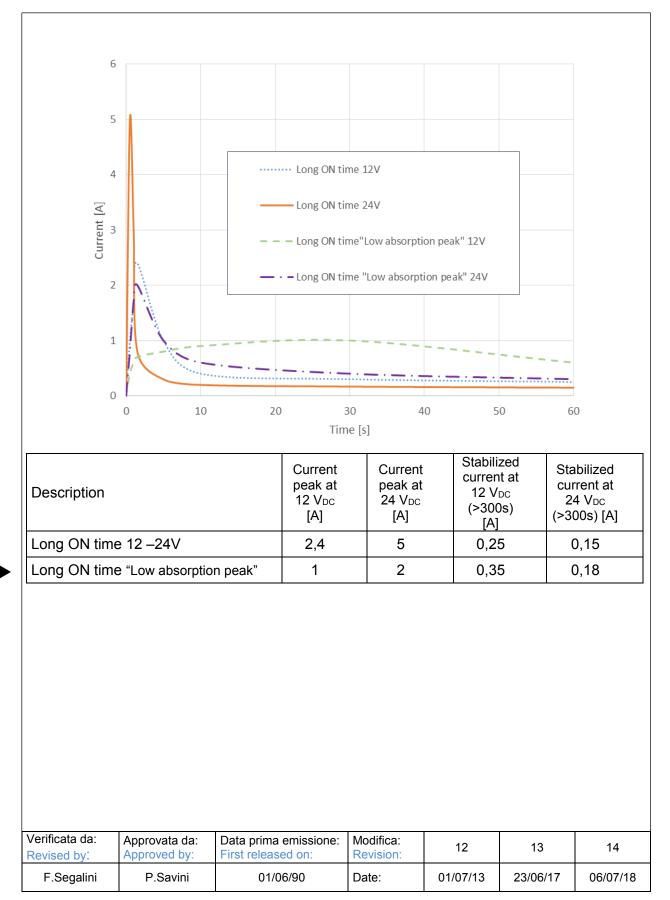


Description	Peak current at 110 V [A]	Peak current at 220 V [A]	Steady state current time [s]	Stabilized current at 110V [ARMS]	Stabilized current at 220V [ARMS]
Long ON time 110 –240V	0,5	1,5	>300	0,05	0,03
Short ON time 110 –240V	0,5	0,75	>120	0,06	0,03

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5.4 Distance through insulation

In conformity with EN 60730-1 par.20. Insulation class II.

5.5 *Resistance through insulation and dielectric strength* According to EN 60730–2–14 par. 13.

6 PERFORMANCE

The thermoactuator's performance is correlated with the following applicable variations:

- counteracting load applied (up to 100 N);
- Feed time (ON / OFF);
- Voltage ;
- Ambient conditions (temperature / humidity).

On the basis of variables applied, it is possible to determine the more suitable type of thermoactuator among the following construction variables:

- "long time ON" if energized longer than 2 minutes;
- "short time ON" if energized less than or equal to 2 minutes;
- "silicone injected" version for ambient conditions with relative humidity up to 98% and/or presence of electrically conductive dust.

6.1 Useful life

The useful life of a thermoactuator is defined by the number of cycles; that is, the number of strokes performed within the tolerances established.

The useful life is influenced by certain parameters, mainly:

- applied load (see diagram 6.3);
- time ON (see diagram 6.4).

Other important parameters are:

- operating ambient temperature;
- operating ambient relative humidity;

- time OFF (time during which the thermoactuator is not energized.

For all the thermoactuators with "long time ON" and "short time ON, 12/14V, 110/220V, energized with standard cycle 2 min ON – 5 min OFF, at an ambient temperature of 20°C and with a counteracting load of 10 N; the minimum guaranteed life is 18,000 cycles.

An actuator is considered to have reached the end of its life when the stroke is no longer within the defined tolerances. The stroke becomes progressively shorter, this deterioration will be more or less rapid depending on the type of application

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6.2 Stroke/time diagrams

A stroke/time characteristic diagram is associated with each single actuator code. The drawing shows, in scale, the stroke of the plunger vs time; it also identifies the time "range" within which the entire actuator's group is tested, checking that:

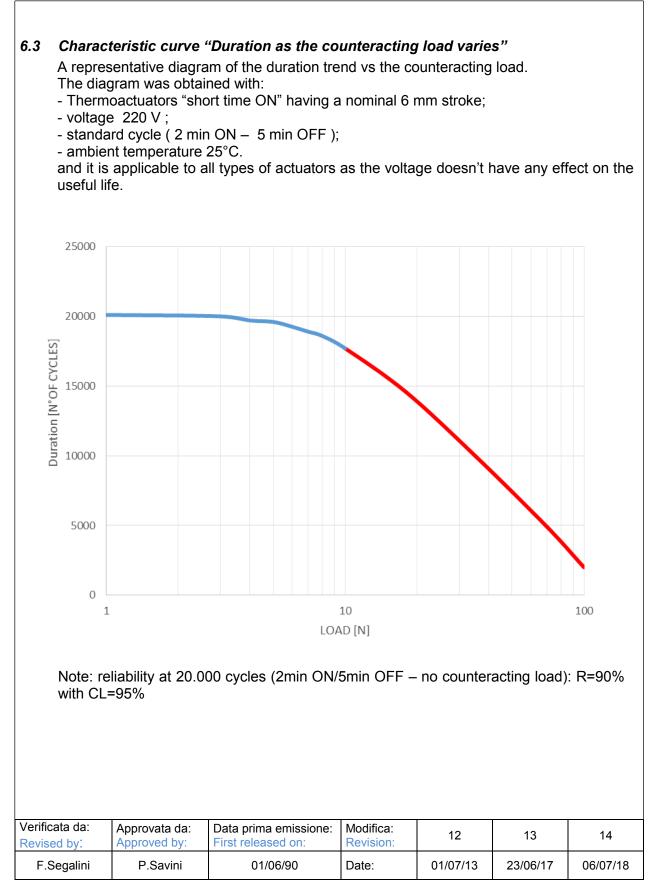
- it performs a stroke equal to the nominal stroke, within a defined time;
- when de-energized it retracts to its initial position, within a defined time;

The diagram clearly shows:

- actuator's nominal stroke with relative tolerance range;
- time ON and time OFF;
- min and max time taken for the plunger to perform its complete stroke;
- min and max time taken for the plunger to retract to its rest position;
- electrical and mechanical characteristics (Enclosure A, table 1);

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Characteristic curve "Duration as the time ON varies" 6.4 A representative diagram of the duration trend vs the time ON. The diagram was obtained with: - Thermoactuators "long time ON" having a nominal 6 mm stroke; - voltage 220 V; - no counteracting load; - ambient temperature 25°C. it is also valid for 110 V silicone injected actuators version and, unless otherwise specified, for 12/24 V actuators. 25000 20000 Duration [N°OF CYCLES] 15000 10000 5000 0 10 1000 1 100 ON TIME [minute] Verificata da: Approvata da: Data prima emissione: Modifica: 12 13 14 Revised by: Approved by: First released on: **Revision:** 01/07/13 06/07/18 F.Segalini P.Savini 01/06/90 Date: 23/06/17

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6.5 Diagram of the duration of changing of counteracting load and ON time phase The diagram is a result of the elaboration of the diagrams data: Duration at the changing of counteracting load Duration at the changing of ON time phase The chart shown below is approximate, to have more precise indications on the duration in the specific conditions of use, the tests on a significant number of pieces have to be borne by the user. 25000 20000 Duration [N°OF CYCLES] 15000 10000 10 18 5000 -Millo 35 70 100 0 10 120 200 720 2 60 ON TIME [minute] Verificata da: Approvata da: Data prima emissione: Modifica: 12 13 14 Revised by: Approved by: First released on: **Revision:** 01/07/13 06/07/18 F.Segalini P.Savini 01/06/90 Date: 23/06/17

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6.6	A represe The curve The diagonal - thermo	entative diagr ves differ from gram was obta	ing a 6 mm nominal s	ie total strok ype of actua	e time vs th		cting load.
160)						
140)						
120)			••••••			-
100)						
Time [s])						
F 60)						_
40)						
			LONG ON TIME 12V/110V	LONG	ON TIME 24V/2	220V	
20)		SHORT ON TIME 110V	- · - SHOR	T ON TIME 220	/	
0		10 20	30 40 50 Load [N		70 80	90	100
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6.7 Characteristic curve "Start delay"

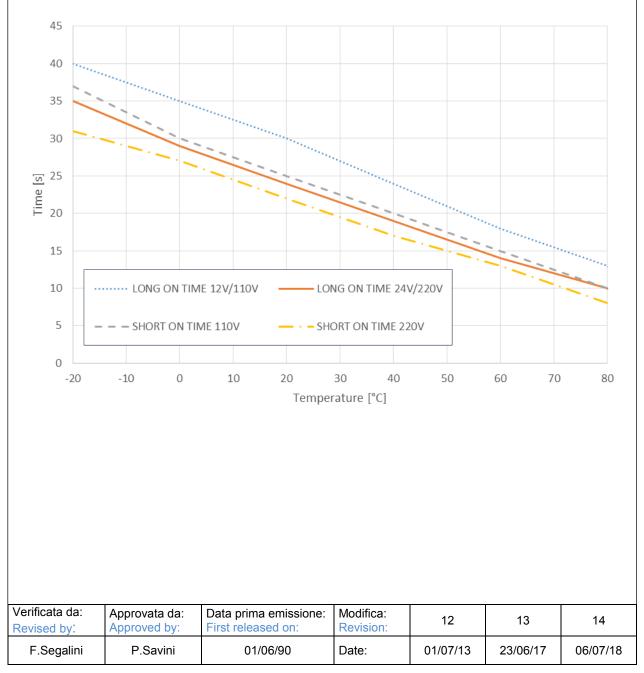
The "start delay" is the time interval before the plunger starts to move after it has been energized.

A representative diagram shown below shows the trend of the delay time vs ambient temperature. The curves differ from one another for the type of thermoactuator and tension.

The diagram was obtained with

- thermoactuator having a 6 mm nominal stroke;

- standard cycle (2 min. ON 5 min. OFF);
- counteracting load 10 N.



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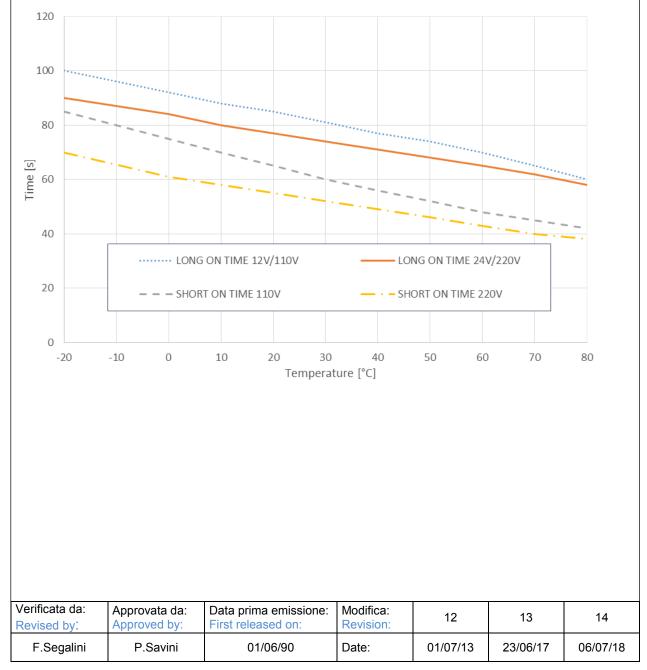


6.8 Characteristic curve "Total stroke time"

The "total stroke time" is the time taken by the device to reach the nominal stroke after it has been energized.

A representative diagram of the trend of total stroke time vs ambient temperature. The curves differ from one another for each type of actuator and voltage. The diagram was obtained with:

- thermoactuators having a 6 mm nominal stroke;
- standard cycle (2 min. ON 5 min. OFF);
- counteracting load 10N.



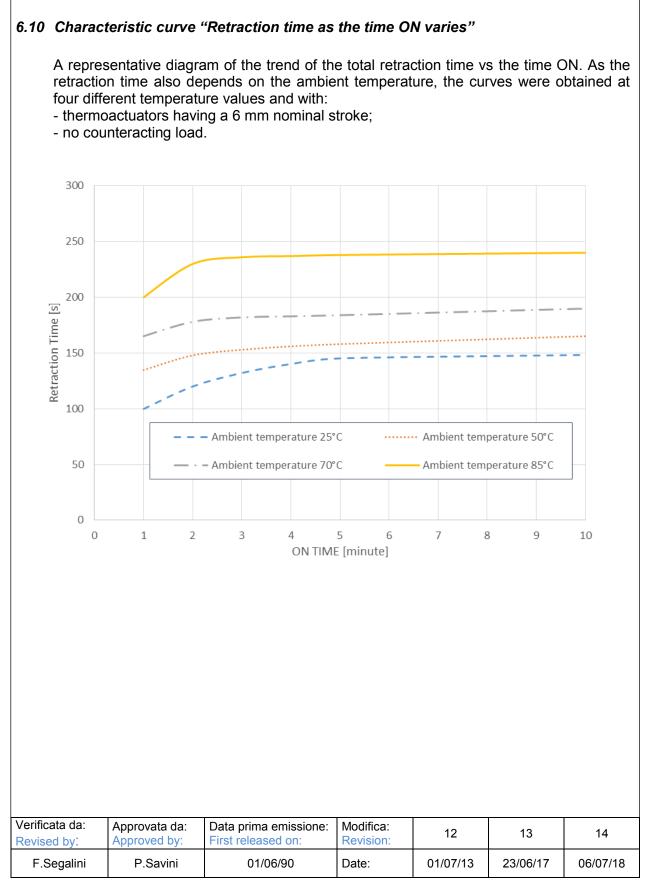
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	The cur The diag - thermo - 2 r	ves differ from ogram was obtai	one another for each ned with: ng a 6 mm nominal s	type of actu			iperature.
	350						
		····· LONG	ON TIME 12V/110V -	LONG ON 1	TIME 24V/220V	7 ,	
	300	_	ON TIME 110V -	- · - SHORT ON			
	250	510101					
	250						
S	200					···	
Time [s]	150						
	150						
	100						
			•				
	50						
	0						
	-20	0	20	40 erature [°C]	60	80	100
			Tempe				
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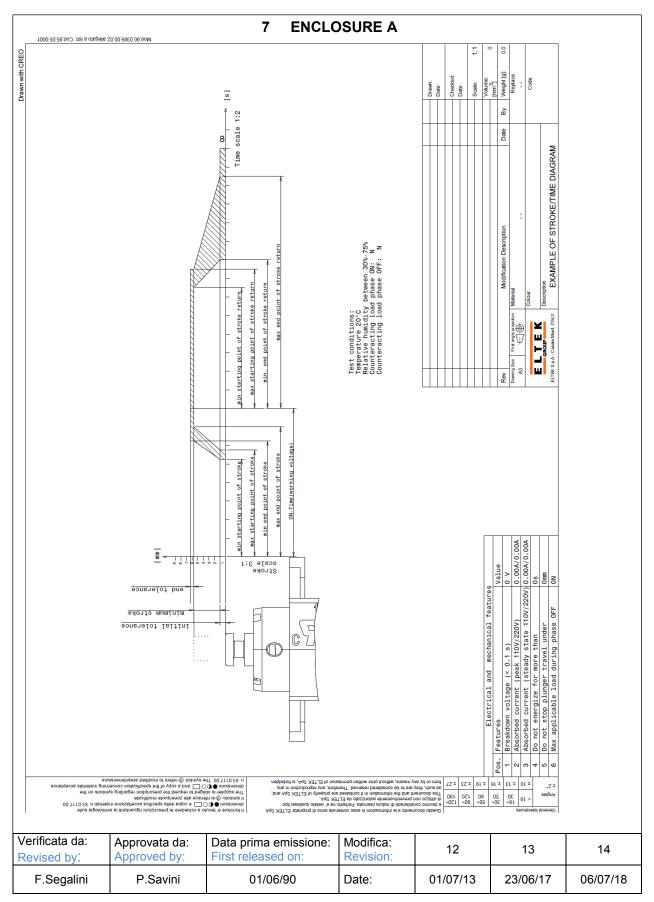




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